GO / GO PLUS

Quick Installation and Programming Guide

ERREKA

This quick guide is a summary of the complete installation guide. The guide contains safety warnings and other explanations that must be taken into account. You can download the latest version of this guide and the installation guide in the "Downloads" section of the Erreka website: http://www.erreka.com.

WARNING The options and functions described in this guide apply for the firmware version indicated on the circuit. The firmware, as part of a process of continuous improvement, is subject to the incorporation of new functionalities or upgrades, and therefore to new versions not necessarily compatible with previous ones. Some options or functions may therefore differ or be unavailable if your firmware is older than shown in this guide.





To remove the upper cover (for GO PLUS models only), it is necessary to turn the lever (P) next to the lower anchor of the balancing springs. This turns the unlocking cam (L).

(A **GO PLUS right-hand** barrier is shown)





Choosing the balancing spring(s)

The balancing springs to be used depend on the length of the barrier arm, the type of arm, and the accessories placed on it (in short, the total weight of the arm).

The attached tables indicate which springs to use, depending on the case. Using other accessories may affect the choice of springs.

If the spring must be changed, it is best to do this before installing the barrier and arm.

GO (GO524BEC) and GO PLUS (GOP24BEC) barriers				
		Type and le	ngth of arm	
Accessories installed	Straight 0-2.5m (AGO02-AGO04)	Straight 2.5-3m (AGO02-AGO04)	Straight 3-4m (AGO02-AGO04) Telescopic 4m (AGO01)	Straight 4-5m (AGO03-AGO05) Telescopic 5m (AGO01)
None LEDs Rubber bar Moving bracket (*) LED Lights + Moving foot Rubber bar + Moving foot	No springs	1x Ø4	1x Ø5 Straight 5m: 1x Ø5	1x Ø4 + 1x Ø5 Straight 6m (GO standard configuration): 1x Ø4 + 1x Ø5

GO PLUS barriers (GOP24BEC)			
	Type and length of arm		
Accessories installed	Telescopic 6m (AGO06)	Telescopic 8m (AGO07-AGO08)	
None LEDs Rubber bar Moving bracket (*) LED Lights + Moving foot Rubber bar + Moving foot	2x Ø5 (GO PLUS standard configuration)	2x Ø5 + 2x Ø6 (Ø6 central position - Ø5 lateral position)	

GO PLUS barriers (GOP24BEC)			
	Oval articulated arm 90°		
Accessories installed	Length 3m (AGO11)	Length 4m (AGO10)	Length 5m (AGO09)
None	1x Ø5	2x Ø5	1x Ø4 + 1x Ø6

GO PLUS barriers (GOP24BEC)		
Oval arm with skirt		with skirt
Accessories installed	Length 3m (AGO13-AGO17)	Length 4m (AGO14-AGO18)
None	2x Ø5	1x Ø4 + 1x Ø6

* The fixed (AGO15) or moving (AGO16) bar bracket must be installed for barriers measuring 4m or longer. I™ More arms than those shown in this table can be mounted; see the complete manual for more information.



Mounting on the ground

Prepare a firm base and fasten the barrier with the elements supplied:

- Expansion bolts
- Flatbars
- Washers
- Spring washers
- Nuts

Preparing the arm: length and LED strip

Adjusting arm length:

If the arm is not telescopic, cut it to the required length.

If the arm is telescopic, it is not necessary to cut it; simply adjust its length by inserting more or less of the smaller section into the larger section.



Adjusting the length of the LED strip:

If the arm has been shortened, the LED strip (L) will be too long. Do not cut it; insert the excess inside the arm through the end. Cut the excess from the LED strip's protective cover (P).









Electrical connections

- The M1 motor, FA 24Vdc power supply, and MGN magnetothermal breaker are supplied installed and connected.
- If you have ordered an LED strip (LED), install it as shown in section "Installation of the LED strip" and connect it as set out in section "LED strip connections".



Effect of the PT, PHOTO, LOOP, OPEN, STOP, and CLOSE inputs

		ARM POSITION					
INPUT	Down (closed)	Raising (opening)	Stopped raising (in automatic mode, timing)	Up (open) (in automatic mode, timing)	Lowering (closing)	Stopped lowering (in automatic mode, timing)	
INFRARED Safety on Closing	No effect	Finishes opening	Closing is not allowed in semi- automatic mode. In automatic mode, the timer continues until it reaches DD , at which point it resets	Closing is not allowed in semi- automatic mode. In automatic mode, the timer continues to run and resets when it reaches DD if it remains activated	Stops and reverses the movement until fully open. In automatic mode, it also closes	Closing is not allowed in semi- automatic mode. In automatic mode, the timer continues to run and resets when it reaches 00 if it remains activated	
LOOP Safety on Closing (Immediate closing)	No effect	Finishes opening and closes immediate- ly	Opens fully and then closes	Closing is not allowed in semi- automatic mode, closing immediately when disabled. In automatic mode, it resets standby time and closes immediately when disabled	Stops, reverses the movement until opening, and closes immediately	Opens completely and closes immediately	
PT Step-by-step activation	Opens	Stops In au- tomatic mode, it also times and closes	Closes	Closes	Stops In automatic mode, it also times and closes	Opens	
STOP Stop	Stops while activated	Stops In au- tomatic mode, it also times and closes	In semi-automatic mode, it stops while activated; in automatic mode, it times, stops, and resets the timer	In semi-automatic mode, it stops while activated; in automatic mode, it times, stops, and resets the timer	Stops In automatic mode, it also times and closes, and times, stops, and resets the timer while activated	In semi-automatic mode, it stops while activated; in automatic mode, it times, stops, and resets the timer	
OPEN Opening activation	Opens	No effect	Opens	In semi-automatic mode, it has no effect. In automatic mode, it resets standby time	Stops and reverses until fully open	Opens	
CLOSE Closing activation	No effect	No effect	Closes	Closes	No effect	Closes	





Installation of Radio Receiver

An external receiver such as IRIN2S-250 is required if you wish to use radio transmitters. Refer to the instructions for the receiver you are using.



OPEN-CLOSE ACTIVATION CONNECTION





Complete programming chart

■ Procedure to use the programming display:

- Briefly press SET to access programming. The display will show ארך .
- Press OPEN or CLOSE to move from Menu 11 to the specific menu (e.g. 19).
- Press SET to go to the specific Menu (e.g. **79**).
- Press OPEN or CLOSE to navigate through the different submenus within the Menu.
- Press SET to enter a submenu.
- Press OPEN or CLOSE to navigate through the different options of each submenu.
- Press SET to accept the selected option.
- Press STOP to exit programming.

Menu	Submenu	Options	Parameter	Default option
79	19 F I I0 30 Opening speed (the higher the number, the greater the speed) 22		55	
	F2	10 30	Closing speed (the higher the number, the greater the speed)	18
	F3	00 99	Closing mode and waiting time (seconds) DD : semi-automatic mode, does not close automatically D 199: automatic mode, closes automatically at the end of standby time	00
	FS	00 33	Type of gearbox U8: GO; U9: GO PLUS Other values not in use or for future applications	08: GO 09: GO PLUS
	۴٦	0, 1	Motor turning direction	0
	F8	00	Open/Closed Indicator	00
		01	Voltage Indicator	
		20	Current Indicator	
		03	Speed Indicator	
		04	Hall Sensor Indicator	
		05	Open/Close Indicator	
		06	Record Saved Indicator	
69	U9	0, 1	0: warning light I: green/red lights (traffic light)	1
67	H8	0090	Maximum opening force	δD (60% of the possible maximum)
	H9	0090	Maximum closing force	6 ^Ω (60% of the possible maximum)

	Display indications		
88 (static)	Barrier open		
88 (static)	Barrier closed		
88 (static)	Barrier in intermediate position		
OP (static)	Barrier open		
CL (static)	Barrier closed		
IO, 09, 08	Timing in Automatic Closing mode (10, 09, 08,)		
88 (static)	Barrier in Recording mode P I (Barrier Open Position)		
	\Rightarrow Each time "Open" is pressed it shows OP, and each time "Close" is pressed it shows CL		
60 (Static)	Barrier in Recording mode P2 (Barrier Closed Position) \Rightarrow Each time "Close" is pressed it shows $\mathbb{C}L$, and each time "Open" is pressed it shows $\mathbb{D}P$.		

Error codes				
Code Meaning Solution				
53	The motor runs continuously and exceeds the limit sensors	 Check the connection and wiring of the optical limits (HALL) from the motor. Check the mechanism. 		
83	Motor rotor locked	 Check the mechanism. Check the motor connection. 		
85	Error reading the limit sensors	Check the connection and wiring of the optical limits (HALL) from the motor.		
٤٦	The photocell is activated	Remove the object blocking the photocell beam.		